# ISOCHRONICITY FOR TRIVIAL QUINTIC AND SEPTIC PLANAR POLYNOMIAL HAMILTONIAN SYSTEMS 

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#### Abstract

In this paper we completely characterize trivial isochronous centers of degrees 5 and 7 . Precisely, we provide formulas, up to linear change of coordinates, for the Hamiltonian $H$ of the isochronous centers such that $H=\left(f_{1}^{2}+f_{2}^{2}\right) / 2$ has degrees 6 and 8 , and $f=\left(f_{1}, f_{2}\right): \mathbb{R}^{2} \rightarrow$ $\mathbb{R}^{2}$ is a polynomial map with $\operatorname{det} D f=1$ and $f(0,0)=(0,0)$.


## 1. Introduction

Let $P(x, y)$ and $Q(x, y)$ be real polynomials in the variables $x$ and $y$. We say that a polynomial vector field $\mathcal{X}=(P, Q)$ has degree $n$ when $\max \{\operatorname{deg} P, \operatorname{deg} Q\}=n$. Given a polynomial Hamiltonian $H: \mathbb{R}^{2} \rightarrow \mathbb{R}$ of degree $n+1$, the associated polynomial Hamiltonian system of degree $n$ is

$$
\begin{equation*}
\dot{x}=-H_{y}(x, y), \quad \dot{y}=H_{x}(x, y) . \tag{1}
\end{equation*}
$$

System (1) has a center at $(0,0)$ if there is a neighbourhood of the origin filled of periodic orbits except the origin. The maximum connected set filled of periodic orbits having in its inner boundary the origin is called the period annulus of the center localized at the origin. If the period annulus is $\mathbb{R}^{2} \backslash\{(0,0)\}$, we call the center global. We say that a polynomial Hamiltonian system has an isochronous center at the origin if $(0,0)$ is a center of $(1)$ and all the orbits in the period annulus of the center have the same period.

The following characterization of the polynomial Hamiltonian systems possessing an isochronous center at the origin was given in [6]. The polynomial Hamiltonian system (1) has an isochronous center of period $2 \pi$ at the origin if and only if

$$
\begin{equation*}
H(x, y)=\frac{f_{1}(x, y)^{2}+f_{2}(x, y)^{2}}{2}, \tag{2}
\end{equation*}
$$

for all $(x, y)$ in a neighborhood $N_{0}$ of the origin, where $f=\left(f_{1}, f_{2}\right): N_{0} \rightarrow \mathbb{R}^{2}$ is an analytic map with Jacobian determinant $\operatorname{det} D f$ constant and equal to 1 , and $f(0,0)=(0,0)$. We observe that this characterization still holds for analytic Hamiltonians. When $f$ can be taken polynomial, we say that

[^0]the polynomial Hamiltonian isochronous center is trivial. In this case, it is clear that $f$ will be defined in all $\mathbb{R}^{2}$. From [8], when the center is trivial, it is a global center if and only if $f$ is globally injective. Thus the problem of knowing whether a trivial polynomial Hamiltonian isochronous center is global or not is equivalent to the Jacobian conjecture in $\mathbb{R}^{2}$, which stands that a polynomial map $f: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ with constant Jacobian determinant is globally injective. We mention here that if the degrees of $f_{1}$ and $f_{2}$ are less than or equal to 101 then $f$ is globally injective (see [7] and, for other results on the Jacobian conjecture, see [3]). Thus all the trivial polynomial Hamiltonian isochronous centers of degree less than or equal to 201 are global ones.

In [2] it was proved that all isochronous centers of cubic polynomial Hamiltonian systems are trivial (and hence global) and after a linear change of coordinates the Hamiltonian can be written as

$$
H(x, y)=\left(k_{1} x\right)^{2}+\left(k_{2} y+k_{3} x+k_{4} x^{2}\right)^{2}
$$

where $k_{1}, k_{2}, k_{3}, k_{4} \in \mathbb{R}$ and $k_{1} k_{2} \neq 0$. We also mention that there are no polynomial Hamiltonian isochronous centers of degree 4, see [4]. Moreover, it was proved in [5] that there are no polynomial Hamiltonian isochronous centers of even degree for which the analytical function $f$ of the Hamiltonian (2) is defined in the whole plane. In particular, there are no trivial polynomial Hamiltonian isochronous centers of even degree. On the other hand, there are examples of non-trivial polynomial Hamiltonian isochronous centers of degree $6 k+1$ for all $k \geq 1$, see section 3 . We point out that in these examples the map $f$ is defined in the whole plane. The following are thus natural questions.
Open question 1: Are there non-trivial quintic polynomial Hamiltonian isochronous centers?
Open question 2: Are there non-trivial polynomial Hamiltonian isochronous centers with Hamiltonian (2) such that $f$ is not analytical in the whole plane $\mathbb{R}^{2}$ ?

We observe that if the open question 2 has a negative answer, then by [5] there are no polynomial Hamiltonian isochronous centers of even degree.

Our main result is the characterization of the quintic and the septic trivial polynomial Hamiltonian isochronous centers, see theorems 4 and 5 respectively, where we provide formulas for the Hamiltonian of these systems. We also give an alternative formula for the Hamiltonian of the cubic polynomial isochronous centers (with a trivial proof), using that these centers are trivial, see Proposition 3.

## 2. Trivial polynomial Hamiltonian isochronous centers

We shall use the following technical result.
Lemma 1. Let $p, q: \mathbb{R}^{2} \rightarrow \mathbb{R}$ be homogeneous polynomials of degree $m$ and $n$ respectively such that $\operatorname{det} D(p, q) \equiv 0$. Let also $d=\operatorname{gcd}(m, n)$, we define
$m^{\prime}=m / d$ and $n^{\prime}=n / d$. Then there exists a homogeneous polynomial $r: \mathbb{R}^{2} \rightarrow \mathbb{R}$ of degree $d$ and constants $c_{p}, c_{q} \in \mathbb{R}$ such that $p=c_{p} r^{m^{\prime}}$ and $q=c_{q} r^{n^{\prime}}$.

Proof. It is enough to prove that the rational function $f=p^{n} / q^{m}$ is constant. In order to do that, it is enough to show that $f_{x}=f_{y}=0$. We have

$$
f_{x}=\frac{p^{n-1} q^{m-1}}{q^{2 m}}\left(n q p_{x}-m p q_{x}\right)=\frac{p^{n-1} q^{m-1}}{q^{2 m}} y\left(p_{x} q_{y}-q_{x} p_{y}\right)=0
$$

where in the second equality above we used the Euler's Theorem for homogeneous maps. The proof that $f_{y}=0$ is analogous.

We address the reader to [1] for a much more general version of Lemma 1.

In the proofs of the results of this section, we will have to solve partial differential equations of the form

$$
p_{x}+\beta p_{y}=h
$$

where $p, h: \mathbb{R}^{2} \rightarrow \mathbb{R}$ are homogeneous polynomials of degrees $k$ and $k-1$, respectively, and $\beta \in \mathbb{R}$. By defining $q: \mathbb{R}^{2} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
p(x, y)=q(x, y-\beta x)=q\left(x_{1}, y_{1}\right) \tag{3}
\end{equation*}
$$

the original equation turns to

$$
q_{x_{1}}=h\left(x_{1}, y_{1}+\beta x_{1}\right)
$$

and hence there is $c \in \mathbb{R}$ such that $q\left(x_{1}, y_{1}\right)=\int_{0}^{x_{1}} h\left(s, y_{1}+\beta s\right) d s+c y_{1}^{k}$, and $p$ is given by (3). For further references, we enunciate this procedure in the following result.

Lemma 2. Let $p, h: \mathbb{R}^{2} \rightarrow \mathbb{R}$ be homogeneous polynomials of degrees $k$ and $k-1$, respectively, satisfying $p_{x}+\beta p_{y}=h$, with $\beta \in \mathbb{R}$. Then there is $c \in \mathbb{R}$ such that $p(x, y)=q(x, y-\beta x)$ where $q\left(x_{1}, y_{1}\right)=\int_{0}^{x_{1}} h\left(s, y_{1}+\beta s\right) d s+c y_{1}^{k}$.

We begin with Proposition 3, where we give an alternative characterization of the cubic polynomial Hamiltonian isochronous centers using the fact that they are trivial (recall the mentioned result of [2]). Right after the proof, we relate the formula of Proposition 3 and the one presented in [2].

Proposition 3. Assume that the polynomial Hamiltonian system (1) has degree 3 and has an isochronous center of period $2 \pi$ at the origin. Then up to a linear change of variables, the Hamiltonian can be written as

$$
H=\frac{P^{2}+(y+\lambda P)^{2}}{2}
$$

with $P=x+c_{2} y^{2}, c_{2}, \lambda \in \mathbb{R}$ and $c_{2} \neq 0$.

Proof. Since the cubic polynomial Hamiltonian isochronous centers are trivial, there exists $f=\left(f_{1}, f_{2}\right): \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ a polynomial map of degree 2 with $\operatorname{det} D f=1$ and $f(0,0)=(0,0)$ such that $H=\left(f_{1}^{2}+f_{2}^{2}\right) / 2$. After a linear change of variables, it is clear that we can write

$$
f_{1}=x+p_{2}, \quad f_{2}=y+q_{2}
$$

with $p_{2}$ and $q_{2}$ homogeneous polynomials of degree 2 . Without loss of generality we can assume that $p_{2} \neq 0$ (otherwise we change the roles of $f_{1}$ and $f_{2}$ and of $x$ and $y$ ). The hypothesis $\operatorname{det} D f=1$ also gives that

$$
\begin{equation*}
p_{2 x}+q_{2 y}=0, \quad p_{2 x} q_{2 y}-q_{2 x} p_{2 y}=0 \tag{4}
\end{equation*}
$$

The second equation of (4) gives from Lemma 1 that there exists $\lambda \neq 0$ such that

$$
q_{2}=\lambda p_{2}
$$

Substituting this in the first equation of (4) we obtain $p_{2 x}+\lambda p_{2 y}=0$, which solved for a homogeneous polynomial of degree 2 (by Lemma 2) determines $c_{2} \in \mathbb{R}$ such that

$$
p_{2}=c_{2}(y-\lambda x)^{2}
$$

with $c_{2} \neq 0$. We then apply the change of variables $(x, y) \mapsto(x, y-\lambda x)$, finishing the proof.

We observe that changing $x$ to $y$ and taking $\sqrt{2} k_{1}=1 / \sqrt{1+\lambda^{2}}, \sqrt{2} k_{2}=$ $\sqrt{1+\lambda^{2}}, \sqrt{2} k_{3}=\lambda / \sqrt{1+\lambda^{2}}$ and $\sqrt{2} k_{4}=c_{2} \sqrt{1+\lambda^{2}}$, the formula of Proposition 3 satisfies the mentioned formula for the cubic polynomial Hamiltonian isochronous centers of [2]. On the other hand, the change of coordinates $(x, y) \mapsto \sqrt{2}\left(k_{2} y+k_{3} x, k_{1} x\right)$ transforms the mentioned formula of [2] in $\left.H(x, y)=\left(x+c_{2} y^{2}\right)^{2}+y^{2}\right) / 2$, with $c_{2}=k_{4} /\left(\sqrt{2} k_{1}\right)$, which is the formula of Proposition 3 with $\lambda=0$. We observe that in [2] it was not assumed that the isochronous center has period exactly $2 \pi$.

For trivial polynomial Hamiltonian isochronous centers of degrees 5 and 7 we have similar formulas to the Hamiltonians, see the following theorems 4 and 5.

Theorem 4. Assume that the polynomial Hamiltonian system (1) has degree 5 and has a trivial isochronous center of period $2 \pi$ at the origin. Then up to a linear change of variables, the Hamiltonian can be written as

$$
H=\frac{P^{2}+(y+\lambda P)^{2}}{2}
$$

with $P=x+c_{2} y^{2}+c_{3} y^{3}, c_{2}, c_{3}, \lambda \in \mathbb{R}$ and $c_{3} \neq 0$.
Proof. We consider $H=\left(f_{1}^{2}+f_{2}^{2}\right) / 2$, with $f=\left(f_{1}, f_{2}\right)$ a polynomial map of degree 3 satisfying $f(0,0)=(0,0)$ and $\operatorname{det} D f(x, y)=1$ for all $(x, y) \in \mathbb{R}^{2}$. It is clear that after a linear change of variables we can write

$$
f_{1}=x+p_{2}+p_{3}, \quad f_{2}=y+q_{2}+q_{3}
$$

where $p_{i}$ and $q_{i}$ are homogeneous polynomials of degree $i, i=1,2$. Without loss of generality we can suppose that $p_{3} \neq 0$. The assumption $\operatorname{det} D f=1$ gives

$$
\begin{align*}
p_{2 x}+q_{2 y} & =0 \\
p_{3 x}+q_{3 y}+p_{2 x} q_{2 y}-q_{2 x} p_{2 y} & =0  \tag{5}\\
p_{3 x} q_{2 y}-q_{2 x} p_{3 y}+p_{2_{x}} q_{3 y}-q_{3 x} p_{2 y} & =0 \\
p_{3 x} q_{3 y}-q_{3 x} p_{3 y} & =0
\end{align*}
$$

The last equation gives by Lemma 1 that there exists $\lambda \in \mathbb{R}$ such that

$$
\begin{equation*}
q_{3}=\lambda p_{3} \tag{6}
\end{equation*}
$$

Substituting this in the third equation in (5), we obtain

$$
\begin{equation*}
p_{3 x}\left(q_{2}-\lambda p_{2}\right)_{y}-\left(q_{2}-\lambda p_{2}\right)_{x} p_{3 y}=0 \tag{7}
\end{equation*}
$$

Here we have two possibilities: either $q_{2} \neq \lambda p_{2}$ or $q_{2}=\lambda p_{2}$.
In the first one, equation (7) gives by Lemma 1 that there exist $a, b, c_{2}, c_{3} \in$ $\mathbb{R}$, with $c_{2} c_{3}\left(a^{2}+b^{2}\right) \neq 0$ such that

$$
\begin{equation*}
q_{2}=\lambda p_{2}+c_{2}(a x+b y)^{2}, \quad p_{3}=c_{3}(a x+b y)^{3} \tag{8}
\end{equation*}
$$

Using then the first equation of (8) and the first one of (5), we obtain

$$
p_{2 x}+\lambda p_{2 y}=-2 b c_{2}(a x+b y)
$$

From Lemma 2 , we obtain $d_{2} \in \mathbb{R}$ such that

$$
p_{2}=-b c_{2}((a+b \lambda) x+2 b(y-\lambda x)) x+d_{2}(y-\lambda x)^{2}
$$

Then we substitute $p_{2}$, (8) and (6) in the second equation of (5) and, after dividing by $a x+b y$ and equating the coefficients of $x$ and $y$ to 0 , we obtain the system

$$
\left(\begin{array}{cc}
a & \lambda \\
b & -1
\end{array}\right)\binom{3(a+b \lambda) c_{3}}{4\left(b^{3} c_{2}+(a+b \lambda) d_{2}\right) c_{2}}=\binom{0}{0}
$$

If $a+b \lambda=0$, it follows that $b=0$ (since $c_{2} \neq 0$ ), and hence $a=0$, a contradiction. On the other hand if $a+b \lambda \neq 0$, it follows that $c_{3}=0$, which is again a contradiction.

If now $q_{2}=\lambda p_{2}$, it follows from (6) and from the first and the second equations in (5) that

$$
p_{2 x}+\lambda p_{2 y}=0, \quad p_{3 x}+\lambda q_{3 y}=0
$$

Solving these equations for homogeneous polynomials of degrees 2 and 3 (see Lemma 2), respectively, we obtain $c_{2}, c_{3} \in \mathbb{R}$ such that

$$
p_{2}=c_{2}(y-\lambda x)^{2}, \quad p_{3}=c_{3}(y-\lambda x)^{3}
$$

with $c_{3} \neq 0$. So

$$
\begin{aligned}
& f_{1}=x+c_{2}(y-\lambda x)^{2}+c_{3}(y-\lambda x)^{3} \\
& f_{2}=y+\lambda\left(c_{2}(y-\lambda x)^{2}+c_{3}(y-\lambda x)^{3}\right)
\end{aligned}
$$

Applying the linear change of variables $(x, y) \mapsto(x, y-\lambda x)$, we end the proof of the theorem.

The following is a characterization of trivial polynomial Hamiltonian isochronous centers of degree 7 .

Theorem 5. Assume that the polynomial Hamiltonian system (1) has degree 7 and has a trivial isochronous center of period $2 \pi$ at the origin. Then up to a linear change of variables the Hamiltonian $H$ has one of the following two forms:

$$
\begin{array}{ll}
H=\frac{P_{1}^{2}+\left(y+\lambda P_{1}\right)^{2}}{2}, & P_{1}=x+c_{2} y^{2}+c_{3} y^{3}+c_{4} y^{4} \\
H=\frac{P_{2}^{2}+\left(Q+\lambda P_{2}\right)^{2}}{2}, & P_{2}=x+\beta_{1} Q+\beta_{2} Q^{2}
\end{array}
$$

where $Q=y+\Gamma x^{2}, c_{2}, c_{3}, c_{4}, \beta_{1}, \beta_{2}, \lambda, \Gamma \in \mathbb{R}$ and $c_{4} \beta_{2} \Gamma \neq 0$.
Proof. Let $f_{1}$ and $f_{2}$ be polynomials of degree 4 such that $\operatorname{det} D\left(f_{1}, f_{2}\right)=1$ and $f_{1}(0,0)=f_{2}(0,0)=0$. After a linear change of variables, it is clear we can write

$$
\begin{equation*}
f_{1}=x+p_{2}+p_{3}+p_{4}, \quad f_{2}=y+q_{2}+q_{3}+q_{4} \tag{9}
\end{equation*}
$$

where $p_{i}$ and $q_{i}$ are homogeneous polynomials of degree $i$ for $i=2,3,4$. Moreover, since the homogeneous terms of positive degrees of the Jacobian determinant of $\left(f_{1}, f_{2}\right)$ are zero, we obtain the following equations:

$$
\begin{align*}
p_{2 x}+q_{2 y} & =0,  \tag{10}\\
p_{3 x}+q_{3 y}+p_{2 x} q_{2 y}-q_{2 x} p_{2 y} & =0,  \tag{11}\\
p_{4 x}+q_{4 y}+p_{2 x} q_{3 y}-q_{3 x} p_{2 y}+p_{3 x} q_{2 y}-q_{2 x} p_{3 y} & =0,  \tag{12}\\
p_{2 x} q_{4 y}-q_{4 x} p_{2 y}+p_{4 x} q_{2 y}-q_{2 x} p_{4 y}+p_{3 x} q_{3 y}-q_{3 x} p_{3 y} & =0,  \tag{13}\\
p_{3 x} q_{4 y}-q_{4 x} p_{3 y}+p_{4 x} q_{3 y}-q_{3 x} p_{4 y} & =0,  \tag{14}\\
p_{4 x} q_{4 y}-q_{4 x} p_{4 y} & =0 . \tag{15}
\end{align*}
$$

Equation (15) and Lemma 1 give that

$$
\begin{equation*}
q_{4}=\lambda p_{4} . \tag{16}
\end{equation*}
$$

Substituting this in equation (14) yields

$$
p_{4 x}\left(q_{3}-\lambda p_{3}\right)_{y}-\left(q_{3}-\lambda p_{3}\right)_{x} p_{4 y}=0
$$

We have two possibilities, either

$$
\begin{equation*}
q_{3}=\lambda p_{3} \tag{17}
\end{equation*}
$$

or, from Lemma 1 , there exist $a, b, c_{3}, c_{4} \in \mathbb{R}$ such that

$$
\begin{equation*}
p_{4}=c_{4}(a x+b y)^{4}, \quad q_{3}=\lambda p_{3}+c_{3}(a x+b y)^{3} \tag{18}
\end{equation*}
$$

with $\left(a^{2}+b^{2}\right) c_{3} c_{4} \neq 0$.

Assuming (17), we obtain from (13) that

$$
p_{4 x}\left(q_{2}-\lambda p_{2}\right)_{y}-p_{4 y}\left(q_{2}-\lambda p_{2}\right)_{x}=0
$$

We have then another two possibilities, either

$$
\begin{equation*}
q_{2}=\lambda p_{2} \tag{19}
\end{equation*}
$$

or, from Lemma 1 there exist $a, b, c, c_{2}, c_{4} \in \mathbb{R}$ such that

$$
\begin{equation*}
p_{4}=c_{4}\left(a x^{2}+2 b x y+c y^{2}\right)^{2}, \quad q_{2}=\lambda p_{2}+c_{2}\left(a x^{2}+2 b x y+c y^{2}\right) \tag{20}
\end{equation*}
$$

with $\left(a^{2}+b^{2}+c^{2}\right) c_{2} c_{4} \neq 0$.
Assuming (19), it follows from (16) and (17) that equations (10), (11) and (12) turn to

$$
p_{2 x}+\lambda p_{2 y}=0, \quad p_{3 x}+\lambda p_{3 y}=0, \quad p_{4 x}+\lambda p_{4 y}=0
$$

respectively. Solving these equations for homogeneous polynomials of degrees 2,3 and 4 , we obtain that

$$
p_{2}=c_{2}(y-\lambda x)^{2}, \quad p_{3}=c_{3}(y-\lambda x)^{3}, \quad p_{4}=c_{4}(y-\lambda x)^{4}
$$

By applying the linear change of coordinates $(x, y) \mapsto(x, y-\lambda x)$ in (9), we obtain the first Hamiltonian of the theorem.

Now if we assume (17) and (20), equation (10) turns to

$$
p_{2 x}+\lambda p_{2 y}+2 c_{2}(b x+c y)=0
$$

Using Lemma 2 , we obtain $d_{2} \in \mathbb{R}$ such that

$$
\begin{equation*}
p_{2}=-c_{2}(b x+c y+c(y-\lambda x)) x+d_{2}(y-\lambda x)^{2} . \tag{21}
\end{equation*}
$$

Substituting this in (11), using (17) and (20), we obtain a partial differential equation of the form $p_{3 x}+\lambda p_{3 y}=h$, with

$$
h(x, y+\lambda x)=4\left(b^{2}-a c\right) c_{2}^{2} x^{2}+4 c_{2}\left(b c c_{2}+a d_{2}+b d_{2} \lambda+L \lambda\right) x y+4 c_{2} L y^{2}
$$

where

$$
\begin{equation*}
L=c^{2} c_{2}+d_{2}(b+c \lambda) \tag{22}
\end{equation*}
$$

Then from Lemma 2 , we obtain $d_{3} \in \mathbb{R}$ such that

$$
\begin{align*}
p_{3} & =\frac{4}{3} c_{2}^{2}\left(b^{2}-a c\right) x^{3}+2 c_{2}\left(b c c_{2}+a d_{2}+b d_{2} \lambda+L \lambda\right) x^{2}(y-\lambda x)  \tag{23}\\
& +4 c_{2} L x(y-\lambda x)^{2}+d_{3}(y-\lambda x)^{3} .
\end{align*}
$$

We finally substitute (21) and (23), and also (16), (17) and (20) in equation (12), obtaining an identically zero homogeneous polynomial of degree 3 . Recalling that $\left(a^{2}+b^{2}+c^{2}\right) c_{2} c_{4} \neq 0$, we will divide the analysis in two cases: either $b=-c \lambda$ or $b+c \lambda \neq 0$.

In the first possibility, the coefficient of $y^{3}$ of the polynomial is $8 c c_{2}^{2} L$. Since $L=c^{2} c_{2}$, it follows that $c=0$ (and thus $L=0$ ). Then the coefficient of $x y^{2}$ turns to $-6 a c_{2} d_{3}$, which gives that $d_{3}=0$, and hence the coefficient
of $x^{3}$ gives that $c_{4}=c_{2}^{2} d_{2}$. In particular, $d_{2} \neq 0$. With these information, it follows from (21), (23) and (20) that

$$
p_{2}=d_{2}(y-\lambda x)^{2}, \quad p_{3}=2 a c_{2} d_{2} x^{2}(y-\lambda x), \quad p_{4}=a^{2} c_{2}^{2} d_{2} x^{4}
$$

and $q_{2}, q_{3}$ and $q_{4}$ are given by (20), (17) and (16), respectively. Then by applying the change of coordinates $(x, y) \mapsto(x, y-\lambda x)$ in (9), it follows that in the new variables

$$
\begin{aligned}
& f_{1}=x+d_{2}\left(y^{2}+2 a c_{2} x^{2} y+a^{2} c_{2}^{2} x^{4}\right) \\
& f_{2}=y+\lambda\left(x+d_{2}\left(y^{2}+2 a c_{2} x^{2} y+a^{2} c_{2}^{2} x^{4}\right)\right)+a c_{2} x^{2}
\end{aligned}
$$

By defining $\beta_{2}=d_{2}, \Gamma=a c_{2}$ and $Q=y+\Gamma x^{2}$, we clearly obtain the second Hamiltonian of the theorem with $\beta_{1}=0$.

Now we analyze the second possibility $b+c \lambda \neq 0$. The coefficients of $y^{3}$ and $x y^{2}$ of the polynomial defined by equation (12) give the following linear system (recall that $L$ is given by (22))

$$
\begin{equation*}
A\binom{c_{4}}{d_{3}}=\binom{-8 c c_{2}^{2} L}{8 c_{2}^{2}\left(\left(b^{2}-a c\right) d_{2}+3 c \lambda L\right)} \tag{24}
\end{equation*}
$$

where

$$
A=\left(\begin{array}{cc}
4 c(b+c \lambda) & -6 c_{2}(b+c \lambda) \\
4\left(3 b(b+c \lambda)+a c-b^{2}\right) & -6 c_{2}\left(a-b \lambda-2 c \lambda^{2}\right)
\end{array}\right)
$$

The determinant of $A$ is $48 c_{2}(b+c \lambda)^{3} \neq 0$. Thus $c_{4}$ and $d_{3}$ are given by inverting $A$ in (24). We substitute them in the coefficients of $x^{3}$ and $x^{2} y$ and obtain (using (22)), respectively, that

$$
\frac{4 c_{2}^{3}\left(b^{2}-a c\right)^{2}\left(2 b^{2}+a c+3 b c \lambda\right)}{(b+c \lambda)^{3}}=0, \quad \frac{12 c c_{2}^{3}\left(b^{2}-a c\right)^{2}}{(b+c \lambda)^{2}}=0
$$

which gives that $c \neq 0$ and $a=b^{2} / c$. We finally obtain

$$
a=\frac{b^{2}}{c}, \quad c_{4}=\frac{c_{2}^{2} L}{b+c \lambda}, \quad d_{3}=\frac{2 c c_{2} L}{b+c \lambda}
$$

with $L c(b+c \lambda) \neq 0$. Now from (23) and from (20) (after some calculations)

$$
\begin{align*}
p_{3} & =\frac{2 c_{2} L}{c(b+c \lambda)}(b x+c y)^{2}(y-\lambda x) \\
p_{4} & =\frac{c_{2}^{2} L}{c^{2}(b+c \lambda)}(b x+c y)^{4}  \tag{25}\\
q_{2} & =\lambda p_{2}+\frac{c_{2}}{c}(b x+c y)^{2}
\end{align*}
$$

We consider the change of variables $(x, y) \mapsto((b x+c y) /(b+c \lambda), y-\lambda x)$, whose inverse is the transformation $(x, y) \mapsto(x-c y /(b+c \lambda), \lambda x+b y /(b+$ $c \lambda)$ ). Observe that the determinant of the change is 1 . By applying the
transformation in (21) and in (25), we obtain that

$$
\begin{align*}
p_{2} & =-c_{2}(b+c \lambda) x^{2}+\frac{L}{b+c \lambda} y^{2} \\
p_{3} & =\frac{2 c_{2}(b+c \lambda) L}{c} x^{2} y \\
p_{4} & =\frac{c_{2}^{2}(b+c \lambda)^{3} L}{c^{2}} x^{4}  \tag{26}\\
q_{2} & =\lambda p_{2}+\frac{c_{2}(b+c \lambda)^{2}}{c} x^{2} .
\end{align*}
$$

Therefore

$$
\begin{align*}
p_{2}+p_{3}+p_{4} & =-c_{2}(b+c \lambda) x^{2}+\frac{L}{b+c \lambda}\left(y+\frac{c_{2}(b+c \lambda)^{2}}{c} x^{2}\right)^{2}  \tag{27}\\
& =-c_{2}(b+c \lambda) x^{2}+\beta_{2} Q^{2},
\end{align*}
$$

with $\beta_{2}=L /(b+c \lambda)$ and $Q=y+\Gamma x^{2}$, where $\Gamma=c_{2}(b+c \lambda)^{2} / c$. Then from (9), in the new variables,

$$
\begin{aligned}
f_{1} & =x-\frac{c}{b+c \lambda} y-c_{2}(b+c \lambda) x^{2}+\beta_{2} Q^{2} \\
& =x-\frac{c}{b+c \lambda} Q+\beta_{2} Q^{2} .
\end{aligned}
$$

Similarly, substituting the last equation of (26) and equations (17), (16) and (27) in (9), we get that in the new variables

$$
\begin{aligned}
f_{2} & =\frac{b}{b+c \lambda} y+\frac{c_{2}(b+c \lambda)^{2}}{c} x^{2}+\lambda\left(x-c_{2}(b+c \lambda) x^{2}+\beta_{2} Q^{2}\right) \\
& =Q+\lambda\left(x-\frac{c}{b+c \lambda} Q+\beta_{2} Q^{2}\right) .
\end{aligned}
$$

By defining $\beta_{1}=-c /(b+c \lambda)$, we obtain that the above $f_{1}$ and $f_{2}$ satisfy the second Hamiltonian of the theorem (now with $\beta_{1} \neq 0$ ).

We have yet to analyze possibility (18). The remaining part of the proof will be to show that if we assume this possibility we get a contradiction. We will treat this analyzing two cases: $a=-b \lambda$ and $a+b \lambda \neq 0$.

In the first case, we consider new $c_{3}$ and $c_{4}$ not zero in order that (18) turn to

$$
\begin{equation*}
p_{4}=c_{4}(y-\lambda x)^{4}, \quad q_{3}=\lambda p_{3}+c_{3}(y-\lambda x)^{3} \tag{28}
\end{equation*}
$$

We take the change of coordinates $(x, y) \mapsto(x, y-\lambda x)$. Then using (28) we write equations (10), (11), (12) and (13) in these new variables, where we denote $p_{i}(x, y)=\overline{p_{i}}(x, y-\lambda x)$ and $q_{i}(x, y)=\overline{q_{i}}(x, y-\lambda x), i=2,3,4$ :

$$
\begin{align*}
\bar{p}_{2 x}+\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{y} & =0, \\
\bar{p}_{3 x}+\bar{p}_{2 x} \bar{q}_{2 y}-\bar{q}_{2 x} \bar{p}_{2 y}+3 c_{3} y^{2} & =0,  \tag{29}\\
\bar{p}_{3 x}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{y}-\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{x} \bar{p}_{3 y}+3 c_{3} \bar{p}_{2 x} y^{2} & =0, \\
\left(-4 c_{4}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{x} y+3 c_{3} \bar{p}_{3 x}\right) y^{2} & =0 .
\end{align*}
$$

Integrating the fourth equation of (29) in $y$, we obtain $d_{3} \in \mathbb{R}$ such that

$$
\bar{p}_{3}=\frac{4 c_{4}}{3 c_{3}}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right) y+d_{3} y^{3}
$$

On the other hand, defining $\bar{p}_{2}=a_{1} x^{2}+2 a_{2} x y+a_{3} y^{2}$ and integrating in $y$ the first equation of (29), we obtain $a_{4} \in \mathbb{R}$ such that

$$
\bar{q}_{2}=a_{4} x^{2}+2\left(a_{2} \lambda-a_{1}\right) x y+\left(a_{3} \lambda-a_{2}\right) y^{2}
$$

Then we substitute the above $\bar{q}_{2}$ and $\bar{p}_{3}$ in the second and in the third equations of (29), obtaining two identically zero homogeneous polynomials of degrees 2 and 3 , respectively. We denote this by $h_{2}=0$ and $h_{3}=0$, respectively. The coefficient of $y^{3}$ of $h_{3}$ is $-8 c_{4}\left(a_{4}-a_{1} \lambda\right)^{2} /\left(3 c_{3}\right)$. Since $c_{4} \neq 0$, it follows that $a_{4}=a_{1} \lambda$. Then the coefficient of $x^{2}$ of $h_{2}$ turns to $-4 a_{1}^{2}$, and hence $a_{1}=0$. Finally, the coefficients of $y^{2}$ and $y^{3}$ of $h_{2}$ and $h_{3}$, respectively, are $-4 a_{2}^{2}+3 c_{3}$ and $6 a_{2} c_{3}$, implying that $a_{2}=c_{3}=0$, which is a contradiction.

In the second case we consider the change of variables $(x, y) \rightarrow(a x+$ $b y, y-\lambda x)$ and write $\overline{p_{i}}$ and $\bar{q}_{i}, i=2,3,4$ the maps $p_{i}$ and $q_{i}$ in these new variables, i.e. $p_{i}(x, y)=\overline{p_{i}}(a x+b y, y-\lambda x), q_{i}(x, y)=\overline{q_{i}}(a x+b y, y-\lambda x)$. Then denoting the new variables by $(x, y)$ again, it follows that $\bar{p}_{4}=c_{4} x^{4}$, $\bar{q}_{4}=\lambda \bar{p}_{4}$ and $\bar{q}_{3}=\lambda \bar{p}_{3}+c_{3} x^{3}$, and equations (10), (11), (12) and (13) turn, respectively, to

$$
\begin{align*}
a \bar{p}_{2 x}-\lambda \bar{p}_{2 y}+b \bar{q}_{2 x}+\bar{q}_{2 y} & =0 \\
(a+b \lambda)\left(\bar{p}_{3 x}+\bar{p}_{2 x} \bar{q}_{2 y}-\bar{q}_{2 x} \bar{p}_{2 y}\right)+3 b c_{3} x^{2} & =0 \\
(a+b \lambda)\left(\bar{p}_{3 x}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{y}-\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{x} \bar{p}_{3 y}+4 c_{4} x^{3}\right. &  \tag{30}\\
\left.-3 c_{3} \bar{p}_{2 y} x^{2}\right) & =0 \\
(a+b \lambda)\left(4 c_{4}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{y} x-3 c_{3} \bar{p}_{3 y}\right) x^{2} & =0
\end{align*}
$$

The second and the fourth equations of (30) give, respectively, that

$$
\begin{equation*}
\bar{p}_{3 x}=-\left(\bar{p}_{2 x} \bar{q}_{2 y}-\bar{q}_{2 x} \bar{p}_{2 y}\right)-\frac{3 b c_{3}}{a+b \lambda} x^{2}, \quad \bar{p}_{3 y}=\frac{4 c_{4}}{3 c_{3}}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{y} x \tag{31}
\end{equation*}
$$

Substituting (31) in the third equation of (30), we obtain that

$$
\begin{array}{r}
\left(\bar{p}_{2 x} \bar{q}_{2 y}-\bar{p}_{2 y} \bar{q}_{2 x}+\frac{4 c_{4}}{3 c_{3}}\left(\bar{q}_{2}-\lambda \bar{p}_{2}\right)_{x} x+\frac{3 b c_{3}}{a+b \lambda} x^{2}\right)  \tag{32}\\
-4 c_{4} x^{3}+3 c_{3} \bar{p}_{2 y} x^{2}=0 .
\end{array}
$$

Then defining $\bar{p}_{2}=a_{1} x^{2}+2 a_{2} x y+a_{3} y^{2}$ the first equation of (30) will be a differential equation in $\bar{q}_{2}$. Solving it for a homogeneous polynomial of degree 2 (now it is similar to Lemma 2, but we apply the change of variables $x \mapsto x-b y$ instead and integrate in $y$ ), it follows that there exists $a_{4} \in \mathbb{R}$ such that
$\bar{q}_{2}=a_{4}(x-b y)^{2}-2\left(a a_{1}-a_{2} \lambda\right)(x-b y) y-\left(a\left(a_{2}+a_{1} b\right)-\left(a_{3}+a_{2} b\right) \lambda\right) y^{2}$.

Substituting the above $\overline{p_{2}}$ and $\overline{q_{2}}$ in (32) we obtain an identically zero homogeneous polynomial of degree 3 . The coefficient of $x^{3}$ of this polynomial gives that

$$
-4 c_{4}-\frac{2}{3}\left(a a_{1}+a_{4} b-a_{2} \lambda\right)\left(\frac{8 a_{4} c_{4}}{c_{3}}+\frac{9 b c_{3}}{a+b \lambda}\right)=0
$$

Now we substitute $\overline{p_{2}}$ and $\overline{q_{2}}$ in the equation $\bar{p}_{3 x y}-\bar{p}_{3 y x}=0$ given by (31) and obtain an identically zero homogeneous polynomial of degree 1. The coefficient of $x$ of this polynomial gives that

$$
\frac{16 c_{4}\left(a a_{1}+a_{4} b-a_{2} \lambda\right)}{3 c_{3}}=0
$$

Combining the last two equations, we obtain that $c_{4}=0$, a contradiction.

We observe that the two hamiltonians that appear in Theorem 5 can not be transformed in each other using a linear change of coordinates. This is so because applying the linear change $(x, y) \mapsto(a x+b y, c x+d y)$ in the second Hamiltonian, the only way to make the monomial $x^{8}$ disappear is to take $a=0$. Then to make the monomial $x^{4}$ disappear, we have to take $c=0$. But then we no longer have a change of coordinates.

We also observe that our results give formulas (up to linear change of coordinates) for all the polynomial maps $f=\left(f_{1}, f_{2}\right): \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ such that $\operatorname{det} D f=1, f(0,0)=(0,0)$ and degree of $f$ is 2,3 or 4 . Using these formulas it is very simple to see that such maps are injective.

## 3. Examples of polynomial Hamiltonian isochronous centers

The following example shows that there exist non trivial polynomial Hamiltonian isochronous centers of degree $6 k+1$, for all $k \in\{1,2 \ldots\}$.

Example 6. Let $\lambda \in \mathbb{R}$ and $k \in\{1,2 \ldots\}$. Let $f=\left(f_{1}, f_{2}\right): \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ be defined by

$$
f_{1}=\frac{x+\lambda y^{k}}{\sqrt{1+\left(x+\lambda y^{k}\right)^{2}}}, \quad f_{2}=\frac{\left(x+\lambda y^{k}\right)^{2}+\left(1+\left(x+\lambda y^{k}\right)^{2}\right)^{2} y}{\sqrt{1+\left(x+\lambda y^{k}\right)^{2}}}
$$

It follows that the Jacobian determinant of $f$ is constant and equal to 1. Moreover, taking $H=\left(f_{1}^{2}+f_{2}^{2}\right) / 2$, it is simple to see that $2 H$ is the polynomial

$$
\left(x+\lambda y^{k}\right)^{2}+2 y\left(x+\lambda y^{k}\right)^{2}\left(1+\left(x+\lambda y^{k}\right)^{2}\right)+y^{2}\left(1+\left(x+\lambda y^{k}\right)^{2}\right)^{3}
$$

which clearly has degree $6 k+2$ if $\lambda \neq 0$ (and degree 8 if $\lambda=0$ ). Thus system (1) with Hamiltonian $H$ has an isochronous center of degree $6 k+1$ at the origin if $\lambda \neq 0$ (degree 7 if $\lambda=0$ ).

Lemma 7. The isochronous center presented in Example 6 is non-trivial.

Proof. Suppose on the contrary that the center is trivial. Then there exists a polynomial map $g=\left(g_{2}, g_{2}\right): \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ with det $D g=1$ and $g(0,0)=(0,0)$ such that $g_{1}^{2}+g_{2}^{2}=2 H$. The map $h=g \circ T$, with $T(x, y)=\left(x-\lambda y^{k}, y\right)$ is also polynomial, $\operatorname{det} D h=1, h(0,0)=(0,0)$ and

$$
\widetilde{H}=\frac{h_{1}^{2}+h_{2}^{2}}{2}=\frac{x^{2}+2 y x^{2}\left(1+x^{2}\right)+y^{2}\left(1+x^{2}\right)^{3}}{2}
$$

is a polynomial of degree 8. Thus system (1) with Hamiltonian $\widetilde{H}$ has a trivial isochronous center at the origin. Since $h$ is globally injective (by the mentioned result of [7] or by Theorem 5), it follows from the mentioned result of [8] that this center is global. This is not possible, because the level curve $H=1 / 2$ is not bounded (it is formed by the curves $y=-1 /\left(1+x^{2}\right)$ and $\left.y=\left(1-x^{2}\right) /\left(1+x^{2}\right)^{2}\right)$.

Example 6 with $\lambda=0$ has already appeared in [2].
The following example provide trivial isochronous centers for all even degrees.

Example 8. Let $k \in\{2,3, \ldots\},, \lambda, c_{2}, \ldots, c_{k} \in \mathbb{R}$, with $c_{k} \neq 0$ and $f=$ $\left(f_{1}, f_{2}\right): \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$ be defined by

$$
f_{1}=x+c_{2} y^{2}+\cdots+c_{k} y^{k}, \quad f_{2}=y+\lambda f_{1}
$$

It is clear that $f(0,0)=(0,0)$ and $\operatorname{det} D f=1$. Thus system (1) with the Hamiltonian given by $H=\left(f_{1}^{2}+f_{2}^{2}\right) / 2$ has a trivial polynomial Hamiltonian isochronous center of degree $2 k-1$ at the origin. Since $f$ is clearly injective, this center is global.

## Acknowledgments

The first author is partially supported by a FAPESP-BRAZIL grant 2014/26149-3. The second author is partially supported by a MINECO grant MTM 2013-40998-P, an AGAUR grant number 2014SGR-568, and FP7-PEOPLE-2012-IRSES-316338 and 318999. The third author is partially supported by a FAPESP-BRAZIL grant 2012/18780-0 and a CNPq grant $449655 / 2014-8$. The three authors are also supported by a CAPES CSF-PVE grant 88881.030454/ 2013-01 from the program CSF-PVE

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[^0]:    2010 Mathematics Subject Classification. Primary 34A34 ; Secondary: 34C25, 37C37, 14R15.

    Key words and phrases. Isochronous centers, polynomial Hamiltonian systems, Jacobian conjecture.

