

# Darboux integrability and algebraic limit cycles for a class of polynomial differential systems

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**Abstract** This paper deals with the existence of Darboux first integrals for the planar polynomial differential systems  $\dot{x} = \lambda x - y + P_{n+1}(x, y) + xF_{2n}(x, y)$ ,  $\dot{y} = x + \lambda y + Q_{n+1}(x, y) + yF_{2n}(x, y)$ , where  $P_i(x, y)$ ,  $Q_i(x, y)$  and  $F_i(x, y)$  are homogeneous polynomials of degree  $i$ . Within this class, we identify some new Darboux integrable systems having either a focus or a center at the origin. For such Darboux integrable systems having degrees 5 and 9 we give the explicit expressions of their algebraic limit cycles. For the systems having degrees 3, 5, 7 and 9 and restricted to a certain subclass we present necessary and sufficient conditions for being Darboux integrable.

**Keywords** Darboux first integral, algebraic limit cycles, Abel differential equation

**MSC(2010)** 34A34, 34C07

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## 1 Introduction and statement of the main results

There exist three main open problems in the qualitative theory of real planar differential systems, the distinction between a center and a focus, the determination of the number of limit cycles and their distribution, and the determination of its integrability. The importance for searching first integrals of a given system was already noted by Poincaré [26] in his discussion on a method to obtain polynomial or rational first integrals. One of the classical tools in the classification of all trajectories of a dynamical system is to find first integrals. Giné and Llibre [13, 14] characterized a large classes of polynomial differential systems in terms of the existence of Darboux first integrals. Llibre et al. [20, 21] and Zhang [32] studied the exact upper bound of algebraic limit cycles of polynomial differential systems with the help of Darboux theory of integrability. In this paper, we will extend the results of [13, 14] to a new class of polynomial differential systems on their Darboux integrability and algebraic limit cycles.

We study the following systems:

$$\begin{aligned}\frac{dx}{dt} &= \dot{x} = \lambda x - y + P_{n+1}(x, y) + xF_{2n}(x, y) := P(x, y), \\ \frac{dy}{dt} &= \dot{y} = x + \lambda y + Q_{n+1}(x, y) + yF_{2n}(x, y) := Q(x, y),\end{aligned}\tag{1.1}$$

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