

# Periodic solutions induced by an upright position of small oscillations of a sleeping symmetrical gyrostat

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**Abstract** The aim of this paper is to provide sufficient conditions for the existence of periodic solutions emerging from an upright position of small oscillations of a sleeping symmetrical gyrostat with equations of motion

$$\begin{aligned}\ddot{x} + \alpha\dot{y} - \beta x &= \varepsilon F_1(t, x, \dot{x}, y, \dot{y}), \\ \ddot{y} - \alpha\dot{x} - \beta y &= \varepsilon F_2(t, x, \dot{x}, y, \dot{y}).\end{aligned}$$

being  $\alpha$  and  $\beta$  parameters satisfying  $\Delta = \alpha^2 - 4\beta > 0$  and  $\beta - \frac{\alpha^2}{2} \pm \frac{\alpha\sqrt{\Delta}}{2} < 0$ ,  $\varepsilon$  a small parameter and,  $F_1$  and  $F_2$  smooth periodic maps in the variable  $t$  in resonance  $p:q$  with some of the periodic solutions of the system for  $\varepsilon = 0$ , where  $p$  and  $q$  are positive integers relatively prime. The main tool used is the averaging theory.

**Keywords** Periodic solution · Symmetrical gyrostat · Averaging theory

## 1 Introduction and statement of the main results

The equations of motion of a sleeping gyrostat on the upright position under the influence of small periodic momenta are

$$\begin{aligned}\ddot{x} + \alpha\dot{y} - \beta x &= \varepsilon F_1(t, x, \dot{x}, y, \dot{y}), \\ \ddot{y} - \alpha\dot{x} - \beta y &= \varepsilon F_2(t, x, \dot{x}, y, \dot{y}),\end{aligned}\tag{1}$$

for more details on them see Appendix 2 or papers [6] and [9]. Here the dot denotes derivative with respect to the time  $t$ . The parameter  $\varepsilon$  is small and the smooth functions  $F_1$  and  $F_2$  define the perturbed torques which, in general, are periodic functions in the variable  $t$  and in resonance  $p:q$  with some of the periodic solutions of the sleeping symmetrical gyrostat for  $\varepsilon = 0$ , being  $p$  and  $q$  positive integers relatively prime.

Recall that a gyrostat is a mechanical system  $S$  composed by a rigid solid  $S_1$  to which other bodies  $S_2$  are connected; these other bodies may be variable or rigid, but the key property is that they must not be rigidly connected to  $S_1$ , so that the movements of  $S_2$  with respect to  $S_1$  do not modify the distribution of mass within the compound system  $S$ .

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