International Journal of Bifurcation and Chaos, Vol. 32, No. 12 (2022) 2250184 (23 pages) © World Scientific Publishing Company DOI: 10.1142/S021812742250184X

Limit Cycles of Planar Discontinuous Piecewise Linear Hamiltonian Systems Without Equilibria Separated by Nonregular Curves

Johana Jimenez

Universidade Federal do Oeste da Bahia, 47600000 Bom Jesus da Lapa, Bahia, Brazil jjohanajimenez@gmail.com

Jaume Llibre

Departament de Matemàtiques, Universitat Autònoma de Barcelona, 08193 Bellaterra, Barcelona, Catalonia, Spain jllibre@mat.uab.cat

Claudia Valls

Departamento de Matemática, Instituto Superior Técnico, Universidade de Lisboa, Av. Rovisco Pais 1049–001, Lisboa, Portugal cvalls@math.ist.utl.pt

Received March 25, 2022; Revised July 4, 2022

The problem of determining the existence, maximum number and positions of the limit cycles of the planar discontinuous piecewise linear differential systems is an important problem in the qualitative theory of differential systems. In this paper, we study two families of piecewise linear Hamiltonian systems without equilibria in \mathbb{R}^2 separated by a nonregular curve. We provide the maximum number of crossing limit cycles that each family can have and show when this maximum is reached. In this way we are solving for each family the extended 16th Hilbert problem.

Keywords: Crossing limit cycle; discontinuous piecewise linear Hamiltonian system; nonregular curve.

1. Introduction and Statement of the Main Results

A discontinuous piecewise differential system on \mathbb{R}^2 is a pair of \mathbb{C}^r (with $r \geq 1$) differential systems in \mathbb{R}^2 separated by a smooth curve Σ . The *line* of discontinuity Σ of the discontinuous piecewise differential system is given by $\Sigma = h^{-1}(0)$, where $h : \mathbb{R}^2 \to \mathbb{R}$ is a \mathbb{C}^1 function having 0 as a regular value. Observe that Σ is the boundary between the regions $\Sigma^+ = \{(x, y) \in \mathbb{R}^2 | h(x, y) > 0\}$ and

$$\Sigma^{-} = \{(x, y) \in \mathbb{R}^{2} \mid h(x, y) < 0\}. \text{ Hence}$$
$$Z(x, y) = \begin{cases} X(x, y), & \text{if } h(x, y) \ge 0, \\ Y(x, y), & \text{if } h(x, y) \le 0, \end{cases}$$
(1)

is the vector field corresponding to a piecewise differential system with line of discontinuity Σ .

When the vector fields X and Y coincide on the line Σ we have a *continuous piecewise differential system* on \mathbb{R}^2 , that in general will not be smooth on Σ .