

Darboux invariants for planar polynomial differential systems having an invariant conic

Jaume Llibre, Marcelo Messias and Alisson C. Reinol

Abstract. We characterize all the planar polynomial differential systems with a unique invariant algebraic curve given by a real conic and having a Darboux invariant.

Mathematics Subject Classification (2010). 34C05 · 34C99.

Keywords. Polynomial differential systems · Invariant conics · Darboux integrability · Darboux invariant.

1. Introduction and statement of the main results

Real planar polynomial differential systems appear in many branches of applied mathematics, physics, and, in general, in applied sciences. For such differential systems, the existence of a first integral determines completely their phase portrait. The first integrals depending on the time, i.e., on the independent variable of the differential system, are called invariants. A special class of invariants is the Darboux invariants. As we shall see the invariants instead of determining the phase portrait of the system, we determine its α - and ω -limit sets in the compactified polynomial differential system. That is, the Darboux invariants allow to describe the sets where all the orbits born or die.

In general, it is a very difficult problem to recognize when a given polynomial differential system in the plane has or not a first integral or a Darboux invariant. The goal of this paper is to classify all polynomial differential systems in the plane \mathbb{R}^2 having a Darboux invariant and a unique invariant algebraic curve given by a conic.

Let $\mathbb{K}[x, y]$ be the ring of the polynomials in the variables x and y with coefficients in \mathbb{K} , where \mathbb{K} is either \mathbb{R} or \mathbb{C} . We consider the *polynomial differential system* in \mathbb{R}^2 defined by

$$\dot{x} = P(x, y), \quad \dot{y} = Q(x, y), \quad (1)$$

where $P, Q \in \mathbb{R}[x, y]$, P and Q are relatively prime in $\mathbb{R}[x, y]$, and the dot denotes derivative with respect to the independent variable t usually called the *time*.

We say that $m = \max\{\deg P, \deg Q\}$ is the *degree* of system (1). We associate with system (1) the vector field

$$X = P(x, y) \frac{\partial}{\partial x} + Q(x, y) \frac{\partial}{\partial y}.$$

The first author is partially supported by the MINECO/FEDER grant MTM2008-03437, the Generalitat de Catalunya Grant 2009SGR-410, ICREA Academia, and two Grants FP7-PEOPLE-2012-IRSES 316338 and 318999. The second author is supported by CNPq-Brazil Grant 308315/2012-0 and by FAPESP Grant 12/18413-7. The third author is supported by FAPESP Grant 2013/01743-7. All the authors are supported by the Int. Coop. Proj. CAPES/MECD-TQED II and PHB-2009-0025.