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Dynamics, integrability and topology for some classes of Kolmogorov Hamiltonian systems in \mathbb{R}_+^4

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Abstract

In this paper we first give the sufficient and necessary conditions in order that two classes of polynomial Kolmogorov systems in \mathbb{R}_+^4 are Hamiltonian systems. Then we study the integrability of these Hamiltonian systems in the Liouville sense. Finally, we investigate the global dynamics of the completely integrable Lotka–Volterra Hamiltonian systems in \mathbb{R}_+^4 . As an application of the invariant subsets of these systems, we obtain topological classifications of the 3-submanifolds in \mathbb{R}_+^4 defined by the hypersurfaces $axy + bzw + cx^2y + dxy^2 + ez^2w + fz^2w^2 = h$, where a, b, c, d, e, f, w and h are real constants.

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1. Introduction and statement of the main results

Kolmogorov systems are defined by the system of ordinary differential equations

$$\frac{dx_i(t)}{dt} = x_i(t) P_i(x_1(t), \dots, x_n(t)), \quad i = 1, \dots, n \quad (1)$$

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