LIMIT CYCLES FOR A CLASS OF THREE-DIMENSIONAL POLYNOMIAL DIFFERENTIAL SYSTEMS

JAUME LLIBRE and JIANG YU

ABSTRACT. Perturbing the system $\dot{x} = -y(1+x)$, $\dot{y} = x(1+x)$, $\dot{z} = 0$ inside the family of polynomial differential systems of degree n in \mathbb{R}^3 , we obtain at most n^2 limit cycles using the first-order averaging theory. Moreover, there exist such perturbed systems having at least n^2 limit cycles.

1. INTRODUCTION AND STATEMENT OF THE MAIN RESULTS

We perturb the system $\dot{x} = -y(1+x)$, $\dot{y} = x(1+x)$, $\dot{z} = 0$ inside a class of polynomial differential systems of degree n in \mathbb{R}^3 . We note that the unperturbed system has the straight line x = 0, y = 0 and the plane x = -1 filled by singular points. Moreover, each plane $z = z_0 = \text{const}$ is invariant with respect to the flow of the unperturbed system. In fact, on every plane $z = z_0$, the singular point $(0, 0, z_0)$ is a center.

Theorem 1. We consider the family of systems

$$\begin{aligned} \dot{x} &= -y(1+x) + \varepsilon(ax + F(x, y, z)), \\ \dot{y} &= x(1+x) + \varepsilon(ay + G(x, y, z)), \\ \dot{z} &= \varepsilon(cz + R(x, y, z)), \end{aligned} \tag{1}$$

where F(x, y, z), G(x, y, z), and R(x, y, z) are polynomials of degree n starting from terms of degree 2. Then there exists sufficiently small $\varepsilon_0 > 0$ such that, for $|\varepsilon| < \varepsilon_0$, there exist systems (1) having at least n^2 limit cycles bifurcating from the periodic orbits of the system $\dot{x} = -y(1+x)$, $\dot{y} = x(1+x)$, $\dot{z} = 0$.

Theorem 1 improves the results of [1], where, perturbing the system $\dot{x} = -y$, $\dot{y} = x$, $\dot{z} = 0$ inside the same class of polynomial vector fields, the averaging method up to the first order only can obtain at most n(n-1)/2

531

1079-2724/07/1000-0531/0 \bigodot 2007 Springer Science+Business Media, Inc.

²⁰⁰⁰ Mathematics Subject Classification. 37G15, 37D45.

Key words and phrases. Linear center, limit cycle, averaging theory, polynomial differential system.