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Algebraic limit cycles in polynomial systems of differential equations^{*}

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Abstract

Using elementary tools we construct cubic polynomial systems of differential equations with algebraic limit cycles of degrees 4, 5 and 6. We also construct a cubic polynomial system of differential equations having an algebraic homoclinic loop of degree 3. Moreover, we show that there are polynomial systems of differential equations of arbitrary degree that have algebraic limit cycles of degree 3, as well as give an example of a cubic polynomial system of differential equations with two algebraic limit cycles of degree 4.

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1. Introduction

By definition, a planar polynomial system of differential equations is a system of the form

$$\frac{\mathrm{d}x}{\mathrm{d}t} = \dot{x} = P(x, y), \qquad \frac{\mathrm{d}y}{\mathrm{d}t} = \dot{y} = Q(x, y), \tag{1}$$

where P and Q are real polynomials in the variables x and y. The *degree i* of the polynomial system of differential equations is the maximum of the degrees of the polynomials P and Q. In what follows, a planar polynomial system of differential equations of degree 2 or 3 will be called simply a *quadratic* or a *cubic* system, respectively.

In 1900, Hilbert [16] in the second part of its 16th problem proposed to find an estimation of the uniform upper bound for the number of limit cycles of all polynomial systems of differential equations of a given degree, and also to study their distribution or configuration

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